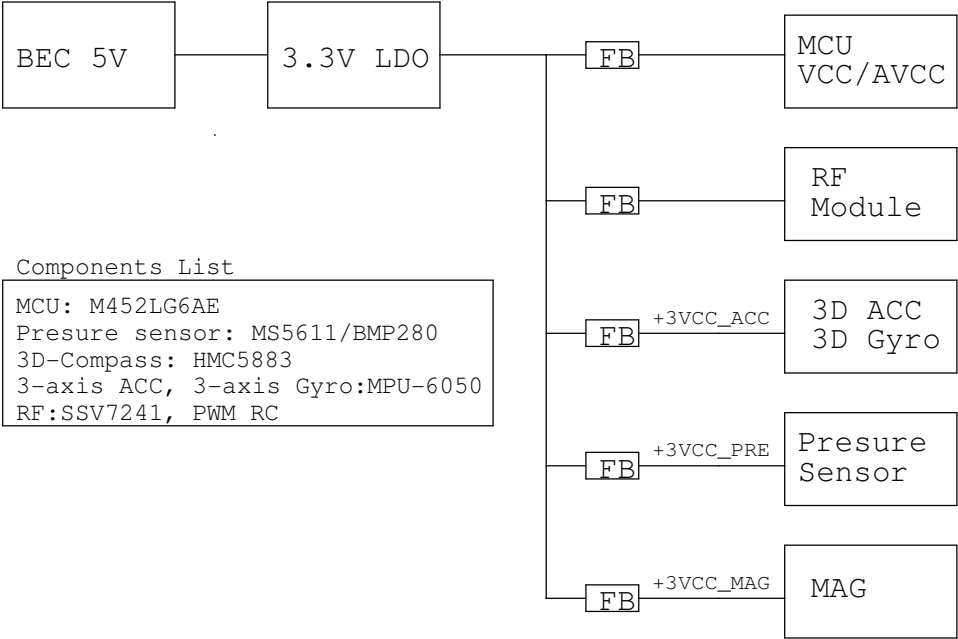


AIO quadcopter / M45X

Revision History	
Rev #	AIO quadcopter
1.4	First Edition - AIO quadcopter / M45X

- 1. BMP280 interface change from SPI to I2C
- 2. Modify 3.3V power to sensor



Components List
MCU: M452LG6AE
Presure sensor: MS5611/BMP280
3D-Compass: HMC5883
3-axis ACC, 3-axis Gyro:MPU-6050
RF:SSV7241, PWM RC



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Nuvoton Technology Corporation

TITLE: M45X & SensorReference Schematics

CHIP NAME	M45Y
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Thursday, April 16, 2015

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